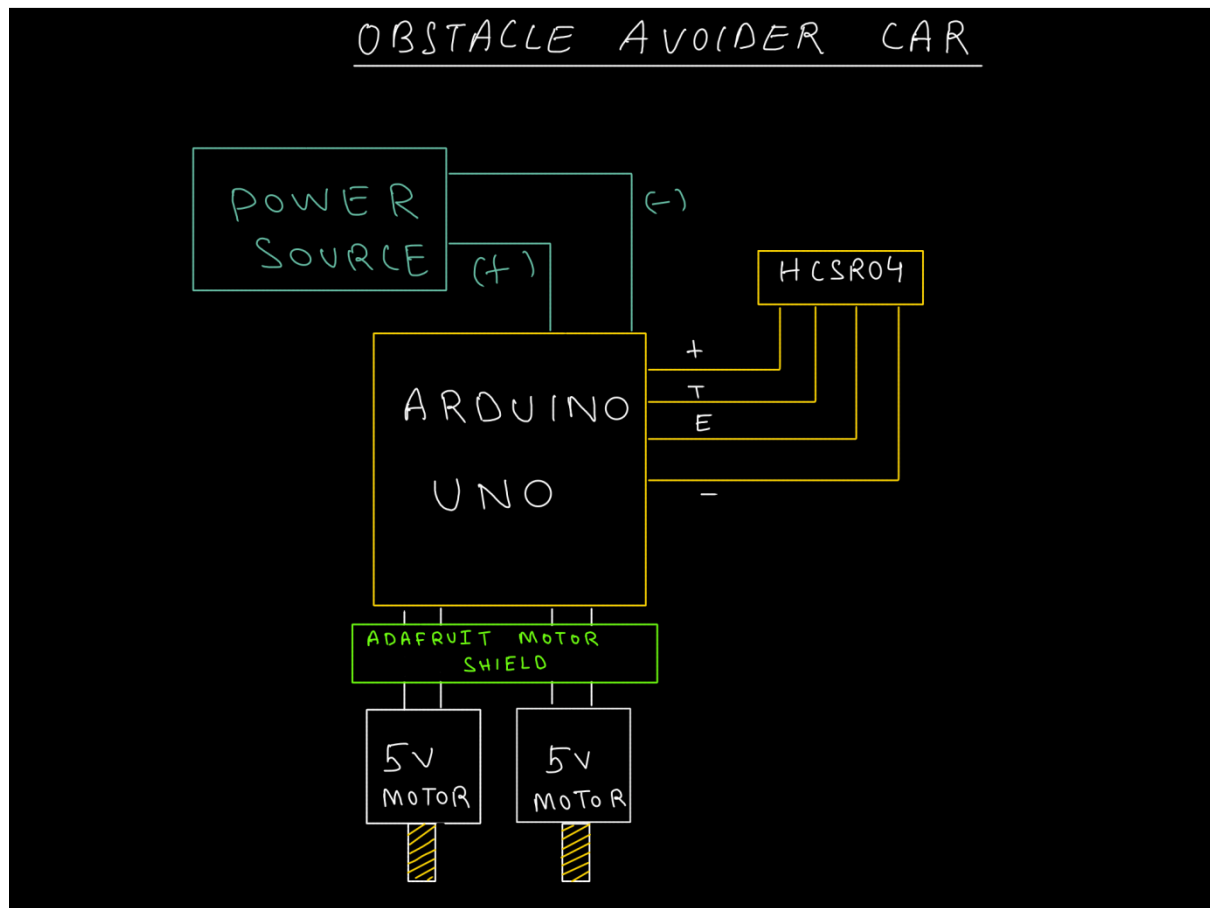<u>**OBSTACLE AVOIDER CAR**</u>

<u>**Description:**</u> The integrated ATL project Obstacle Avoider Car has been ideated to develop an autonomous vehicle which can identify the objects present in front of it and can find a best way to continue its journey.

<u>**Materials Required:**</u>

1. Arduino Uno (Micro-controller)
2. Ultrasonic Sensor(Distance calculator)
3. Adafruit Motor Shield (Motor Driver)
4. Jumper Wires
5. 5v Dc Motors
6. Battery (As power Source)

<u>**Images Of The Model:**</u>

<u>**Achievements:**</u>

<u>**Team:**</u>